## Daya Bay Offline Software: A Status Report Daya Bay Reactor Neutrino Experiment

### Xinchun Tian



Daya Bay Experiment Basics Daya Bay Offline Software

## Outline



Neutrino Physics Basics

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## Outline



1 Neutrino Physics Basics

- 2 Daya Bay Experiment Basics
  - Daya Bay Detector
  - Statistics & Systematics
  - Sensitivity

## Outline



Neutrino Physics Basics

- 2 Daya Bay Experiment Basics
  - Daya Bay Detector
  - Statistics & Systematics
  - Sensitivity
- 3 Daya Bay Offline Software
  - Road-map
  - Framework Basics
  - TES/AES Implementation
  - Data Processing Stages
  - Software organization & Installation

## Neutrino Physics Basics

Mass eigenstates are different with flavor eigenstates

• Pontecorvo-Maki-Nakagawa-Sakata (PMNS) Matrix

$$\begin{pmatrix} \nu_e \\ \nu_\mu \\ \nu_\tau \end{pmatrix} = \begin{pmatrix} U_{e1} & U_{e2} & U_{e3} \\ U_{\mu 1} & U_{\mu 2} & U_{\mu 3} \\ U_{\tau 1} & U_{\tau 2} & U_{\tau 3} \end{pmatrix} \begin{pmatrix} \nu_1 \\ \nu_2 \\ \nu_3 \end{pmatrix}$$

The PMNS matrix can be parameterized as

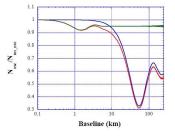
 $\begin{pmatrix} \mathbf{v}_{e} \\ \mathbf{v}_{\mu} \\ \mathbf{v}_{\tau} \end{pmatrix} = \begin{pmatrix} \mathbf{c}_{12} & \mathbf{s}_{12} & \mathbf{0} \\ -\mathbf{s}_{12} & \mathbf{c}_{12} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{1} \end{pmatrix} \begin{pmatrix} \mathbf{1} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{c}_{23} & \mathbf{s}_{23} \\ \mathbf{0} & -\mathbf{s}_{23} & \mathbf{c}_{23} \end{pmatrix} \begin{pmatrix} \mathbf{c}_{13} & \mathbf{0} & \mathbf{s}_{13} \mathbf{e}^{i\delta} \\ \mathbf{0} & \mathbf{1} & \mathbf{0} \\ -\mathbf{s}_{13} \mathbf{e}^{-i\delta} & \mathbf{0} & \mathbf{c}_{13} \end{pmatrix} \begin{pmatrix} \mathbf{1} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{e}^{i\omega/2} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{e}^{i\omega/2+i\beta} \end{pmatrix} \begin{pmatrix} \mathbf{v}_{1} \\ \mathbf{v}_{2} \\ \mathbf{v}_{3} \end{pmatrix}$   $12 \text{ sector } 23 \text{ sector } 13 \text{ sector mass sector solar/reactor atm./acce. } \mathbf{reactor/acce.} \quad \mathbf{0}\nu\beta\beta$ 

 $\theta_{13}$  is the gateway of CP violation in lepton sector!

## Neutrino Physics Basics

### Reactor antineutrino disappearance probability

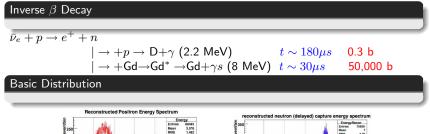
$$P_{ee} \approx 1 - \sin^2 2\theta_{13} \sin^2 \left(\frac{\Delta m_{31}L}{4E_{\nu}}\right) - \cos^4 \theta_{13} \sin^2 2\theta_{12} \sin^2 \left(\frac{\Delta m_{21}L}{4E_{\nu}}\right)$$

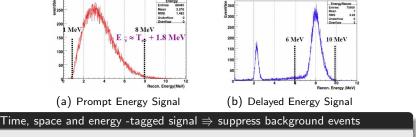


 $\bar{\nu}_e$  disappearance at short baseline (~2km): unambiguous measurement of  $\theta_{13}$ 

Daya Bay Detector Statistics & Systematics Sensitivity

## Detection of $\bar{\nu_e}$

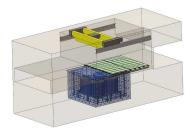




Daya Bay Detector Statistics & Systematics Sensitivity

## Daya Bay Detector

- Anti-neutrino Detector
- Veto Muon System
  - RPC
  - Water Cerenkov



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Daya Bay Detector Statistics & Systematics Sensitivity

## Statistics & Systematics

## Goal of Daya Bay Experiment

 $\sin^2 2\theta_{13} < 0.01$  @ 90% C.L.

### **Statistics**

Near Site	Far Site
0.05%	$\leq 0.24\%$

### **Systematics**

Source of Uncertainty	Near Site Far Sit			
Reactor Related	$\leq$ 0.2%			
Detector Related	$\leq$ 0.38%/module			
Background Related	0.3% per site	0.2%		

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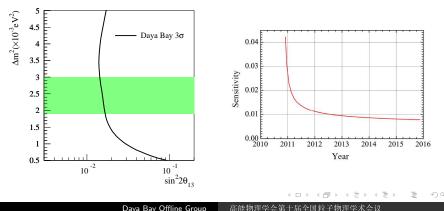
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Sensitivity

## Sensitivity

## Sensitivity @ 90% C.L. with "baseline" detector uncertainties

The sensitivity will be based on the rate and spectral shape analysis



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#### Road-map

Framework Basics TES/AES Implementation Data Processing Stages Software organization & Installation

## Road-map

- Gaudi as framework (developed by LHCb)
- Other LHCb projects
  - lcgcmt, lhcb
- CMT for software Management
- Subversion as software repository
- Geant4 for Simulation
- dybinst as the auto-installer
- Object-Oriented Programming
- $\bullet\,$  External packages, all the  $3^{rd}$  party support softwares
  - AIDA, CMake, HepPDT, Python, Boost, Geant4, MySQL, ROOT, CLHEP, GSL, OpenMotif, XercesC, CMake, GCCXML, HepMC, OpenScientist

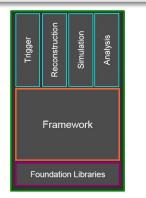
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Road-map Framework Basics TES/AES Implementation Data Processing Stages Software organization & Installation

## Overview of our frameworks's structure

### Software Organization

- Applications using framework components (Algorithms, Services, *etc.*)
- Provides basic services, common interfaces, data exchange and persistency mechanisms, interactivity
- Basic libraries (STL, ROOT, GSL, *etc.*)



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Road-map Framework Basics TES/AES Implementation Data Processing Stages Software organization & Installation

## Brief outline of the various features of the Gaudi framework

- Algorithm
  - user written module, execute() called once per event
  - execution sequence defined at runtime
- AlgorithmTool
  - called on demand, shared between multiple Algorithms
  - managed by ToolSvc
- Service
  - software component provided by framework, available globally
- DataObject
  - atomic data unit
- Transient Data Store
  - repository for DataObjects, used by Algs. and Tools to exchange data
  - framework manages insertion and retrieval, life cycle, load on demand
  - multiple instances: Event, Detector, Histogram
- Converter
  - conversion between transient and persistent formats
- Property
  - runtime modifiable parameters controlling behavior of Algorithms and Services

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## TES/AES Implementatio (LBNL)

### Daya Bay TES & AES

- In Gaudi the TES is cleared before each processing cycle
  - HEP = Beam Crossing, Daya Bay = Readout
- Daya Bay needs access to previous Readout and their derived data
  - e.g., anti-neutrino is a neutron combined with a positron from previous Readout
- Daya Bay's TES has an extra dimension
  - The Archive Event Store (AES)
- Objects placed in the TES are automatically copied into the AES
- For an object in the TES, the AES has a correlated collection of objects
  - "front" object in AES collection is the "most recent"
  - TES collections are collections of collections in AES
  - Paths in the AES are the same as the TES

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## Data Processing Stages

- Generation & kinematics stage
- Detector simulation & hits stage (SimuAlg/DetSim)
- Electronics simulation & digits stage
- Trigger/Readout stage
- Reconstruction stage
- Physics Analysis stage

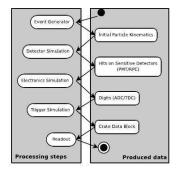


Figure: General processing steps on the left and their input and output data on the right

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## Generation & kinematics stage (BNL, IHEP, IIT)

### GenTools

- Provides a full featured kinematic generator package
- Supports writing to Gaudi TES, Gaudi configuration mechanism
- Generation of Initial Kinematics
  - kinematics = spatial/temporal vertex, particle types and 4-momenta
  - Model all initial interactions that we don't want to leave for Geant4
- Kinematics Data
  - HepMC::GenEvent: vertex, an event number, process ID HepMC::GenVertex: 4-vertex, type, incoming/outgoing particles HepMC::GenParticle: static and dynamic particle quantities
  - Default location in TES: /Event/Gen/HepMCEvents, a simple collection of HepMC::GenEvents

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## Generation & kinematics stage – continue

### Suite of Existing Tools

- GtHepEvtGenTool
  - Converts sources of HEPEvt formatted data
- GtGunGenTool
  - Parameterized particle generation
- GtPositionerTool
  - Generate a vertex (3-vertex)
- GtTimeratorTool
  - Set event time based on an average rate

## GenTools Algorithms

- GtGenerator
  - Driving algorithm for a simple processing model (single event type push)
- GtHepMCDumper
  - Dump generator information to terminal

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Detector simulation & hits stage (SDU, IHEP, BNL)

### Detector simulation

- Geant4-based G4dyb (XML & C++ based Geometry)
- Gaudi-based G4dyb (XML & C++ based Geometry)
- Gaudi-based G4dyb (GDML based Geometry)
- Gaudi-based DetSim (DetDesc based Geometry)

### Hits storage

- Event Data Model
- Persistency
- Algorithm
- Converter

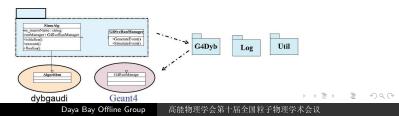
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## Gaudi-based G4dyb (XML & C++ based Geometry)

- Just for testing of Gaudi framework to give users some feeling how it works
- Keep most of the characteristics of the legacy G4dyb
  - Geometry: XML + C++
  - The interfaces to generator via pipe or reading from files unchanged
- Wrapping G4dyb as one algorithm (SimuAlg) in order for launching the simulation job in Gaudi
- Storing hits into TES and write them out into ROOT Ntuple files via THistSvc



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## Gaudi-based DetSim (DetDesc based Geometry)

### Geometry - DetDesc

#### What is DetDesc

- C++ classes/objects for ini-memory representation
- An XML schema for in-file representation

#### Detector Description forms

- XML Files: The source of (ideal) description TDS Objects: The full description as objects from Gaudi TDS Geant4 Geometry: TDS objects are convertible to G4 geometry objects for detector simulation
- When necessary, an alignment DB can be built to supply offsets to TDS objects and thus to G4

#### Detector Description Sections

- Materials: The makeup of all materials Geometry: The full hierarchy of logical/physical volume containment Structure: The parallel, subset hierarchy of important Detector Elements
- The Surface and Tabproperty ("tabulated properties") sections for defining properties

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Gaudi-based DetSim (DetDesc based Geometry) - continue

### Detector Simulation - DetSim

- MC integration method using G4 to track individual particles
- Runs in the Gaudi framework
- Uses the GiGa<sup>1</sup> package to organize Geant4 user code
- Uses the GiGaCnv package to convert detector description to G4 geometry objects
- Initial kinematics generated by the GenTools package
- Produces SimEvent objects
- Supports multiple processing models

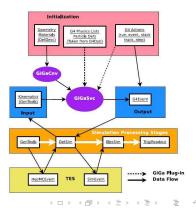
<sup>&</sup>lt;sup>1</sup>G4 Interface for Gaudi Applications or Gaudi Interface for G4 Applications のへの Daya Bay Offline Group 高能物理学会第十届全国粒子物理学术会议

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### Gaudi-based DetSim (DetDesc based Geometry) - continue

### Interface to Geant4

- $\bullet \ \ DetDesc \rightarrow G4 \ geometry$
- PhysList classes from G4dyb
- Action classes for unobservable statistics & trajectory recording
- Kinematics in, G4 data out
- DetSim algs interface between Kinematics & GiGa/G4 and TES
- Simple linear processing model shown as example



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Electronics simulation & digits stage (Caltech, LBNL, IIT)

### Motivation

- Simulation can help the Electronics Design
- Simulation can help the small effects understanding
  - Pulse shaping (Effect of reflections?)
  - Pileup ( $\sim$  of IBD events? Low-energy pileup?)
  - Dark hits (~ of channels?)
  - Many other effects

## Status & Plan

- Electron Simulation package (ElecSim) is almost done!
- Gaudi Integration Provide Gaudi interface to Electronics Simulation
  - Wrap each tool in a corresponding GaudiAlg
  - Allow ESObjects to be put in TES/TDS
  - Add "Pull" capability to GESSimHitReader & GESReadoutStreamer

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## Trigger/Readout stage (Caltech, LBNL, IIT)

### Status

## Trigger Simulation

TrigSim figures out when the trigger conditions are met, and issues a trigger. This trigger then
cross triggers all other appropriate detectors. It is also possible to explicitly issue a trigger at a user
defined clock cycle (External Trigger).

## Readout Simulation

ReadoutSim uses the trigger information which consists of a clock cycle and trigger type to calculate a readout window which is the same for all channels. The FPGA processing then figures out which values are readout for each channel. The values can be different for each channel.

### Plan

Migrate all the code into Gaudi and make it work

Factor out functionality of the code into a Gaudi Tool so that it can be used both in this stand-alone

configuration and also in the "pull" model

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## AD Reconstruction (IHEP)

### Status

- Two methods implemented
  - Charge Maximum Likelihood Fitting
  - Time Maximum Likelihood Fitting

### Plan

- Integration with Gaudi
- Geometry from DetDesc
- Reconstruction Event Data Model

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## Muon Reconstruction (IHEP, BNL)

### Status

- Two kinds of events (Initial value has effect on Rec.)
  - RPC & water events: initial value given by RPC  $\sigma\sim 0.26~{\rm m}$
  - water events: initial value given by PMT  $\sigma \sim 0.48~{\rm m}$
- $\sigma \sim 0.34$  m is achievable

### Plan

• Trying to use better reconstruction method for type-2 muon events

## Software organization

### Software organization

- Package
  - Basic unit of CMT work
- Project
  - A logical unit of releasable software
- Product
  - A deliverable set of one or more projects
- Release
  - An immutable snapshot of a project or product

### СМТ

## Configuration management Tool

• CMT is a very flexible system that organizes: source code, build process, runtime environment.

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## SVN (Server @IHEP, Mirror @NTU)

### Subversion

SVN is a Software Configuration Management tool

- Next generation source code management system
- Acts as a shared, journaled file system

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Daya Bay o	offline repository			
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35/		View Log		3CML
ybgaudi/		View Log		XML
4dyb/		View Log		XML
audi/		View Log		SPHL.
toups/		View Log		XML
astallation/		View Log		XML
egemt/		View Log		XPHL.
		View Log		36ML
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## NuWa (女娲) Installations with dybinst

### NuWa is the name of our offline software

- In Chinese mythology, ...
- In some lazy American English pronunciations which you will often hear around here in Long Island, could be taken to mean "newer" which is somehow fitting for our ever changing software.
- In Japanese, the phrase "Nu Wa" might mean "I'm talking about the neutrino". As in "nu wa daisuki" meaning "this is neutrino, i like".

### dybinst will install

- CMT the basis of our build and runtime setup
- external packages all the  $3^{rd}$  party support software
- LHC projects software taken from LHC effort (lcgcmt, gaudi, lhcb)
- dybgaudi the project holding our Daya Bay specific offline software

### dybinst usage

dybinst help

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## Major Milestones

Mile. No. Milestone Description	WBS	Date
0 US CD-0 Approve Mission Need		Nov-05
Chinese Funding Secured		March-07
6 CD-3a Approval & Long Lead Contract Award		March-08
27 PMT Dry Run & Offline Software Integration Challenge	1.5	18-Dec-08
45 Begin Overall System Testing - DB Near Hall		1-Sep-09
46 DB Near Hall Physics Ready		6-Oct-09
66 Begin Overall System Testing - Far Hall		8-Sep-10
67 Far Hall Physics Ready		13-Oct-10
68 US CD-4a Approval Request		Feb-11

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# Thank you!

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